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APPENDIX 1: SOURCE CODE

TITLE:

ACCEPTING USER CONTROL

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```
'* Name : Snap
'* Author : Neil Gelfond
'* Notice: Copyright (c) 2002 Bose Corporation
                                    : All Rights Reserved
 '* Date : 08/18/03
 '* Version: 1.4
 '* Notes:
 'This program runs on the PIC Mother Board
 ' and send actual ascii codes
 'cmcon
                                                        = 7
                                                                                                       'disable comparitors
OPTION REG.7 = 0
                                                                                                                                     'enable weak pull-ups
adcon1
                                                    =$0e
switch
                                              var porta.0
                                                                                                                                                                                                                      e^{-2\pi i \frac{1}{2} \frac{1
tx
                                      var portb.2
tx2
                                         var portb.7
mode
                                                 var word
                                                                        '9600 non-inverted
'mode = 84
'mode = 16468 '9600 inverted
mode = 188
                                                                        '4800 non-inverted
'mode = 16572
                                                                                   '4800 inverted
define adc bits 8
define adc clock 3
define adc sampleus 50
value
                                                   var byte
                                                         var byte
res value
zone
                                                 var byte
prev_zone
                                                          var byte
current zone var byte
zone_buff var byte[3]
input switch
'define hser rcsta 90h
'define hser txsta 20h
'define hser baud 4800
'define hser spbrg 12
```

pinA var porta.3 pinB var porta.4 pinC var portb.0 pinD var portb.1 input pinA input pinB input pinC input pinD counterA var word counterB var word counterC var word counterD var word bufcount var word ticcount var byte tempstateA var bit tempstateB var bit tempstateC var bit tempstateD var bit prevstateA var bit prevstateB var bit prevstateC var bit prevstateD var bit stateA var bit var bit stateB stateC var bit stateD var bit flagA var bit flagAP var bit flagB var bit flagBP var bit flagC var bit flagCP var bit flagD var bit flagDP var bit limit con 3

PlusMinus

var byte

```
old_PlusMinus var byte
          var byte[3]
buffer
dir
         var byte
           var byte
pulsedata
ticcount = 0
      = 0
dir
pulsedata = 0
flagA
        =0
flagAP
         =0
flagB
        = 0
flagBP
         =0
flagC
        = 0
flagCP
         = 0
flagD
        =0
flagDP
         = 0
stateA
        = pinA
stateB
        = pinB
stateC
        = pinC
stateD
        = pinD
prevstateA = pinA
prevstateB = pinB
prevstateC = pinC
prevstateD = pinD
tempstateA = pinA
tempstateB = pinB
tempstateC = pinC
tempstateD = pinD
counterA = limit
counterB = limit
counterC = limit
counterD = limit
"""ZoneInit""""""
zone_buff(0) = ff
zone buff(1) = ff
zone buff(2) = ff
zone
         =0
```

```
prev_zone = 0
current\_zone = 0
ADCIN 2, value
       = value
value
res_value = value
bufinit:
buffer(0) = ff
buffer(1) = ff
buffer(2) = ff
bufcount = 0
main:
'gosub initialize
gosub Rotory
gosub Direction
gosub BufStuff
gosub Display
*****************
gosub resvalue
gosub Look
gosub a2dbuffer
gosub Press_Test
gosub Release_test
goto main
initialize:
stateA
       = pinA
stateB
       = pinB
```

stateC

= pinC

```
stateD = pinD
prevstateA = pinA
prevstateB = pinB
prevstateC = pinC
prevstateD = pinD
return
"""Rotory""""""
Rotory:
gosub CheckPinA
gosub CheckPinB
gosub CheckPinC
gosub CheckPinD
if (flagA = 1) or (flagB = 1) then
pulsedata.0 = prevstateA
pulsedata.1 = prevstateB
pulsedata.2 = stateA
pulsedata.3 = stateB
flagA = 0
flagB = 0
bufcount = 0
else
if (flagC = 1) or (flagD = 1) then
 pulsedata.0 = prevstateC
pulsedata.1 = prevstateD
 pulsedata.2 = stateC
 pulsedata.3 = stateD
 flagC = 0
 flagD = 0
 bufcount = 0
endif
endif
exit_rotory:
CheckPinA:
if counterA = limit then
goto statecheckA
```

```
else
counterA = counterA + 1
goto countercheckA
endif
countercheckA:
if counter A = limit then
if tempstateA ⇔ pinA then
 goto resetcounterA
else
 prevstateA = stateA
 stateA = tempstateA
 flagA = 1
 flagAP = 1
 goto exitA
endif
else
goto tempstatecheckA
endif
tempstatecheckA:
if tempstateA <> pinA then
goto resetcounterA
else
goto exitA
endif
statecheckA:
if stateA \Leftrightarrow pinA then
goto resetcounterA
else
goto exitA
endif
resetcounterA:
flagA = 0
counter A = 0
tempstateA = pinA
exitA:
return
CheckPinB:
if counterB = limit then
goto statecheckB
```

```
else
counterB = counterB + 1
goto countercheckB
endif
countercheckB:
if counterB = limit then
if tempstateB <> pinB then
 goto resetcounterB
else
 prevstateB = stateB
 stateB = tempstateB
 flagB = 1
 flagBP = 1
 goto exitB
endif
else
goto tempstatecheckB
endif
tempstatecheckB:
if tempstateB <> pinB then
goto resetcounterB
else
goto exitB
endif
statecheckB:
if stateB <> pinB then
goto resetcounterB
else
goto exitB
endif
resetcounterB:
flagB = 0
counterB = 0
tempstateB = pinB
exitB:
return
CheckPinC:
if counterC = limit then
goto statecheckC
```

```
else
counterC = counterC + 1
goto countercheckC
endif
countercheckC:
if counterC = limit then
if tempstateC <> pinC then
 goto resetcounterC
else
 prevstateC = stateC
 stateC = tempstateC
 flagC = 1
 flagCP = 1
 goto exitC
endif
else
goto tempstatecheckC
endif
tempstatecheckC:
if tempstateC <> pinC then
goto resetcounterC
else
goto exitC
endif
statecheckC:
if stateC \Leftrightarrow pinC then
goto resetcounterC
else
goto exitC
endif
resetcounterC:
flagC = 0
counterC = 0
tempstateC = pinC
exitC:
return
CheckPinD:
if counterD = limit then
goto statecheckD
```

```
else
counterD = counterD + 1
goto countercheckD
endif
countercheckD:
if counterD = limit then
if tempstateD \Leftrightarrow pinD then
 goto resetcounterD
else
 prevstateD = stateD
 stateD = tempstateD
 flagD = 1
 flagDP = 1
 goto exitD
endif
else
goto tempstatecheckD
endif
tempstatecheckD:
if tempstateD \Leftrightarrow pinD then
goto resetcounterD
else
goto exitD
endif
statecheckD:
if stateD ⇔ pinD then
goto resetcounterD
else
goto exitD
endif
resetcounterD:
flagD = 0
counterD = 0
tempstateD = pinD
exitD:
return
BufStuff:
if (buffer(1) = \$ff) or (buffer(2) = \$ff) then
'hserout [hex2 buffer(0)," ",hex2 buffer(1)," ",hex2 buffer(2),13,10]
```

```
goto shift
else
dir.0 = buffer(0)
dir.1 = buffer(1)
dir.2 = buffer(2)
endif
gosub ClockCounterClock
                                 Francisco Carlos
shift:
buffer(2) = buffer(1)
buffer(1) = buffer(0)
'hserout [hex2 buffer(0)," ",hex2 buffer(1)," ",hex2 buffer(2),13,10]
return
Direction:
select case pulsedata
case 0,5,10,15
buffer(0) = ff
case 1,7,8,14
buffer(0) = 1
case 2,4,11,13
buffer(0) = 0
                             Salar State States
case 3,6,9,12
buffer(0) = ff
end select
return
ClockCounterClock:
select case dir
case 0,1,2,4
PlusMinus = 45 '(- counter-clock-wise)
case 3,5,6,7
PlusMinus = 43 '(+ clock-wise)
```

```
end select
return
""""Display""""""
Display:
if (flagAP = 1) and (flagBP = 1) then
if old PlusMinus <> PlusMinus then
 'ticcount = 0
 old PlusMinus = PlusMinus
endif
'ticcount = ticcount + 1
if PlusMinus = 45 then
 'high left
 ticcount = ticcount - 1
 if ticcount = 0 or ticcount = 255 then
  ticcount = 30
  ticcount = 16
 endif
 serout2 tx,mode,[$24,$4c,$2b,$2a]
 'serout2 tx2,mode,[$24,$4c,$2b,$2a]
 'serout2 tx,mode,[dec ticcount,13,10] '[PlusMinus,13,10]
 'hserout [dec ticcount,13,10] '[PlusMinus,13,10]
 'pauseus 10000
 'low left
else
 'high right
 ticcount = ticcount + 1
 if ticcount = 31 then
 'if ticcount = 17 then
  ticcount = 1
 endif
 serout2 tx,mode,[$24,$4c,$2d,$2a]
 'serout2 tx2,mode,[$24,$4c,$2d,$2a]
 'serout2 tx,mode,[dec ticcount,13,10] '[PlusMinus,13,10]
 'hserout [dec ticcount,13,10] '[PlusMinus,13,10]
 'pauseus 10000
 'low right
                              Just Will English
endif
                               Mark Bury Till
 gosub initialize
 flagAP = 0
 flagBP = 0
```

```
if (flagCP = 1) and (flagDP = 1) then
if old PlusMinus <> PlusMinus then
 'ticcount = 0
 old PlusMinus = PlusMinus
endif
'ticcount = ticcount + 1
if PlusMinus = 45 then
 'high left
 ticcount = ticcount - 1
  if ticcount = 0 or ticcount = 255 then
  ticcount = 30
  ticcount = 16
  endif
  serout2 tx,mode,[$24,$52,$2b,$2a].
  'serout2 tx2,mode,[$24,$52,$2b,$2a]
  'serout2 tx,mode,[dec ticcount,13,10] '[PlusMinus,13,10]
  'hserout [dec ticcount,13,10] '[PlusMinus,13,10]
  'pauseus 10000
  'low left
else
  'high right
 ticcount = ticcount + 1
 if ticcount = 31 then
  'if ticcount = 17 then
  ticcount = 1
  endif
 serout2 tx,mode,[$24,$52,$2d,$2a]
  'serout2 tx2,mode,[$24,$52,$2d,$2a]
 'serout2 tx,mode,[dec ticcount,13,10] '[PlusMinus,13,10]
  'hserout [dec ticcount,13,10] '[PlusMinus,13,10]
  'pauseus 10000
 'low right
                              San State Contraction
endif
                                 A William
 gosub initialize
flagCP = 0
flagDP = 0
endif
```

```
Return
Resvalue:
ADCIN 0, value
if res value <> value then
 pause 50
 res value = value
 goto resvalue
endif
res_value = value
exit resval:
return
Look:
select case res_value
'serout2 tx,mode,["Res Value ",dec res_value,13,10]
                        'top left,232
 case 104,105,106
  zone_buff(0) = $31
  zone = 1
case 92,93,94,95 'left knob
  zone buff(0) = $36
  zone = 6
case 178,179,180,181
                           'bottom left
  zone buff(0) = $32
  zone = 2
case 117,118,119,120,121
                                  'Top Center
  zone = $35
  'zone = 5
                              case 97,98,99,100,101
                           'Bottom Center
  zone = $38
  zone = 8
```

profession in

```
case 210,211,212,213,214
                          'top right
  zone buff(0) = $33
  zone = 3
                                        3...3
                  'Right knob 157,118,162,106,166,165,117
case 129,130,131
  zone buff(0) = $37
  'zone = 7
                            11.
                         'bottom right
case 141,142,143,144
  zone buff(0) = $34
  'zone = 4
'case is < 20
 ' zone = 0
case else
  zone buff(0) = 0
end select
                             The Transfer of Way to
exit lookup:
return
a2dbuffer:
if (zone buff(1) = f) or (zone buff(2) = f) then
goto buff shift
endif
      if zone buff(0) = zone buff(1) then
zone = zone buff(0)
goto clear_buff
endif
if zone buff(0) = zone buff(2) then
zone = zone buff(0)
goto clear buff
endif
if zone_buff(1) = zone_buff(2) then
zone = zone buff(1)
                      goto clear buff
endif
```

```
""""clear buffers"""""".
clear_buff:
zone buff(0) = ff
zone buff(1) = ff
zone buff(2) = ff
pauseus 100
goto exit_a2dbuffer
buff_shift:
zone buff(2) = zone buff(1)
zone_buff(1) = zone_buff(0)
exit a2dbuffer:
Press_Test:
if zone \Leftrightarrow current zone then
if zone \Leftrightarrow 0 then
current zone = zone
gosub press
endif
endif-
exit_press_test:
return
Release Test:
if zone \Leftrightarrow current zone then
gosub release
current_zone = zone
endif
exit rel test:
return
Press:
serout2 tx,mode,[$24,zone,$50,$2a]
'serout2 tx2,mode,[$24,zone,$50,$2a]
```